



# Chapter 4

## Industrial Applications

# Objectives

By the end of this lesson the learner should be able to:

- Discuss how robots are integrated into manufacturing
- Name three methods of preventing unauthorized entry to the robot work area
- Name and explain the operation of five different industrial robot applications
- Name two peripheral devices that might be found in a robot work cell

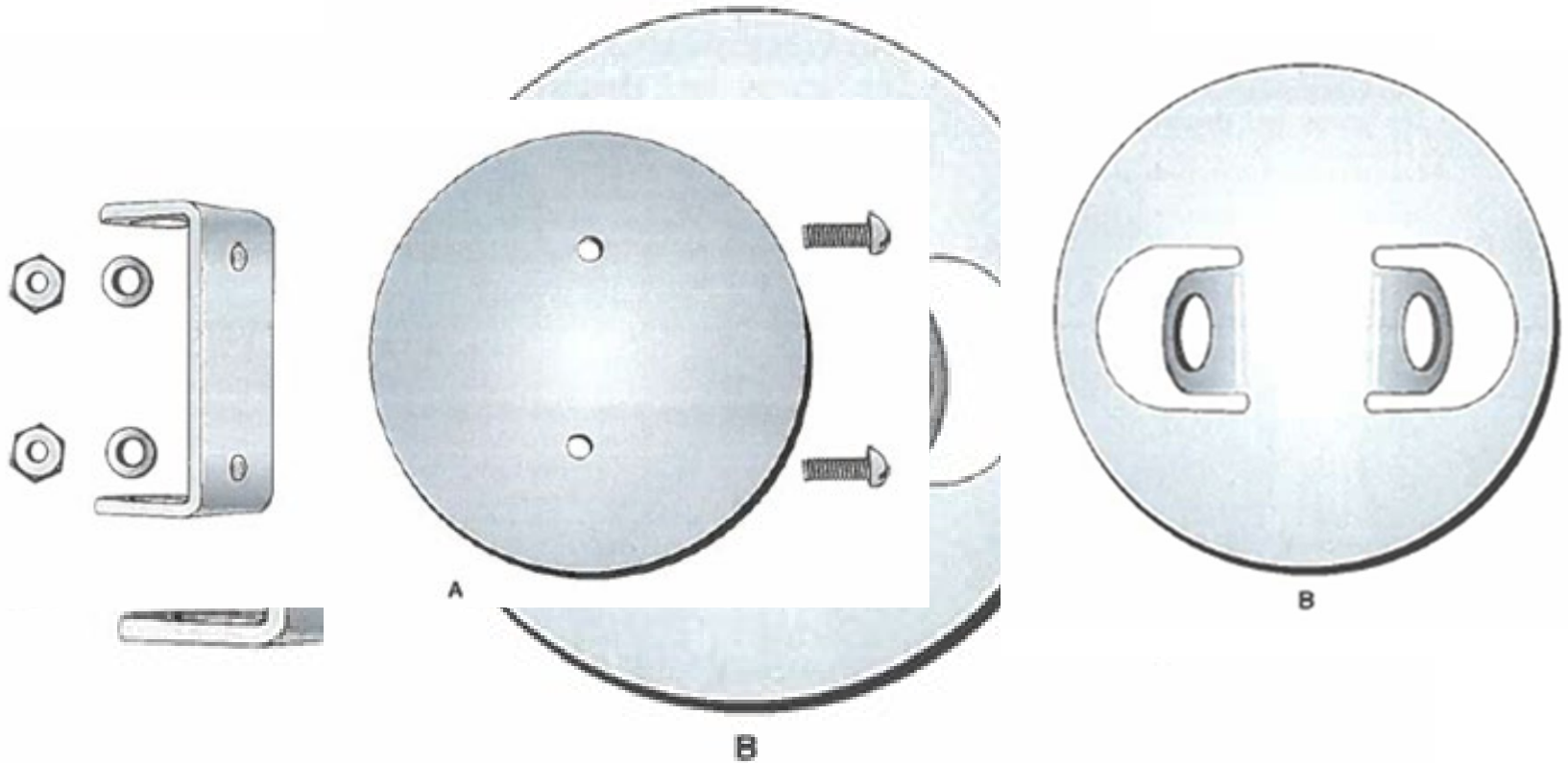
# Key Technical Terms

Accuracy	Command Resolution	Dynamic Performance	Interlocks
Light Curtain	Operational Speed	Payload	Pressure Sensitive Safety Mat
Repeatability	Resolution	Spatial Resolution	

By the end of this lesson the learner should be able to define and explain characteristics / actions related to these technical terms

# Design for Manufacturability

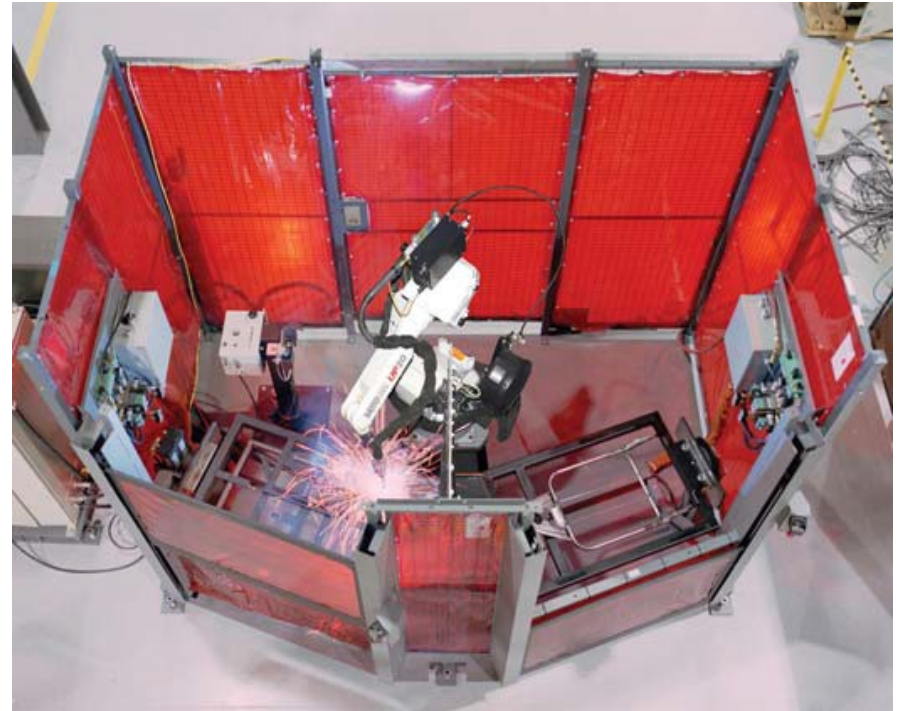
- Figure 'A' - Eight parts to subassembly
  - Difficult for robot to assemble
- Figure 'B' – redesigned to accommodate easier robotic assembly



# Robotic Safety



## Safety Barriers



# Robotic Safety

## Robot Enclosures



# Robotic Safety

## Safety Sensors

- Light curtains
- Pressure Sensitive Safety Mats





# Robot Applications in Industry

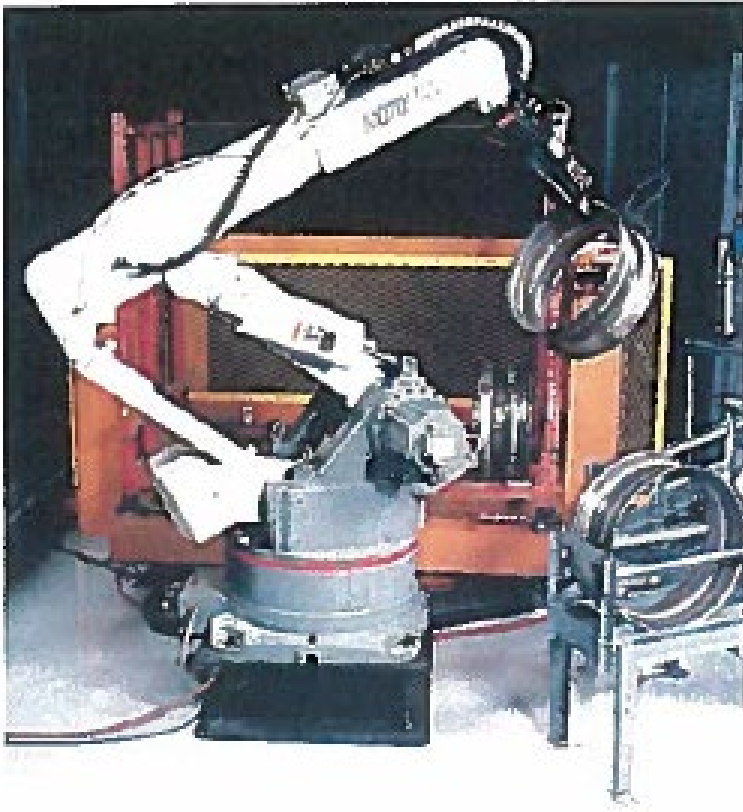
## Palletizing





# Robot Applications in Industry

## Pick and Place



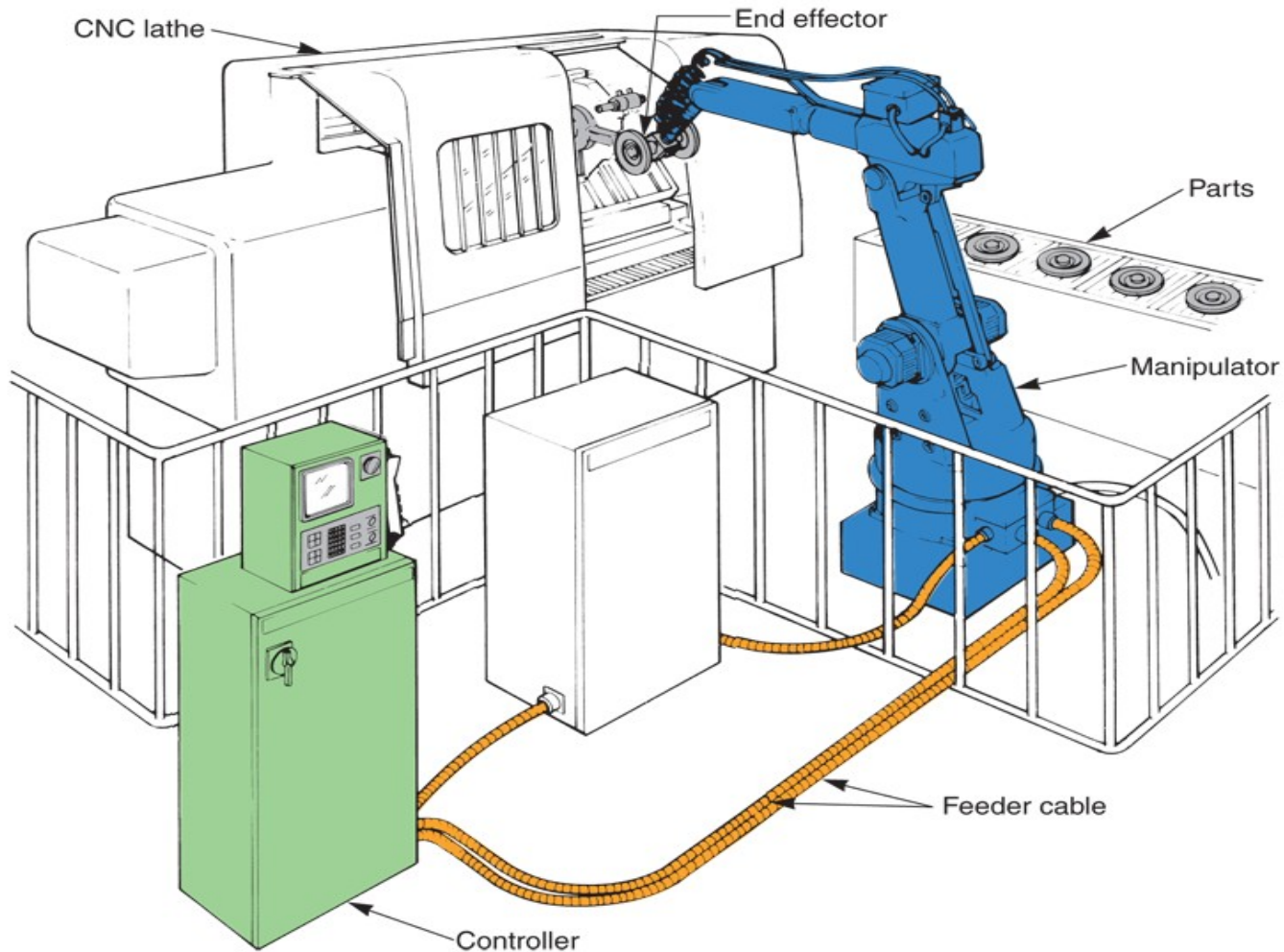
A



B

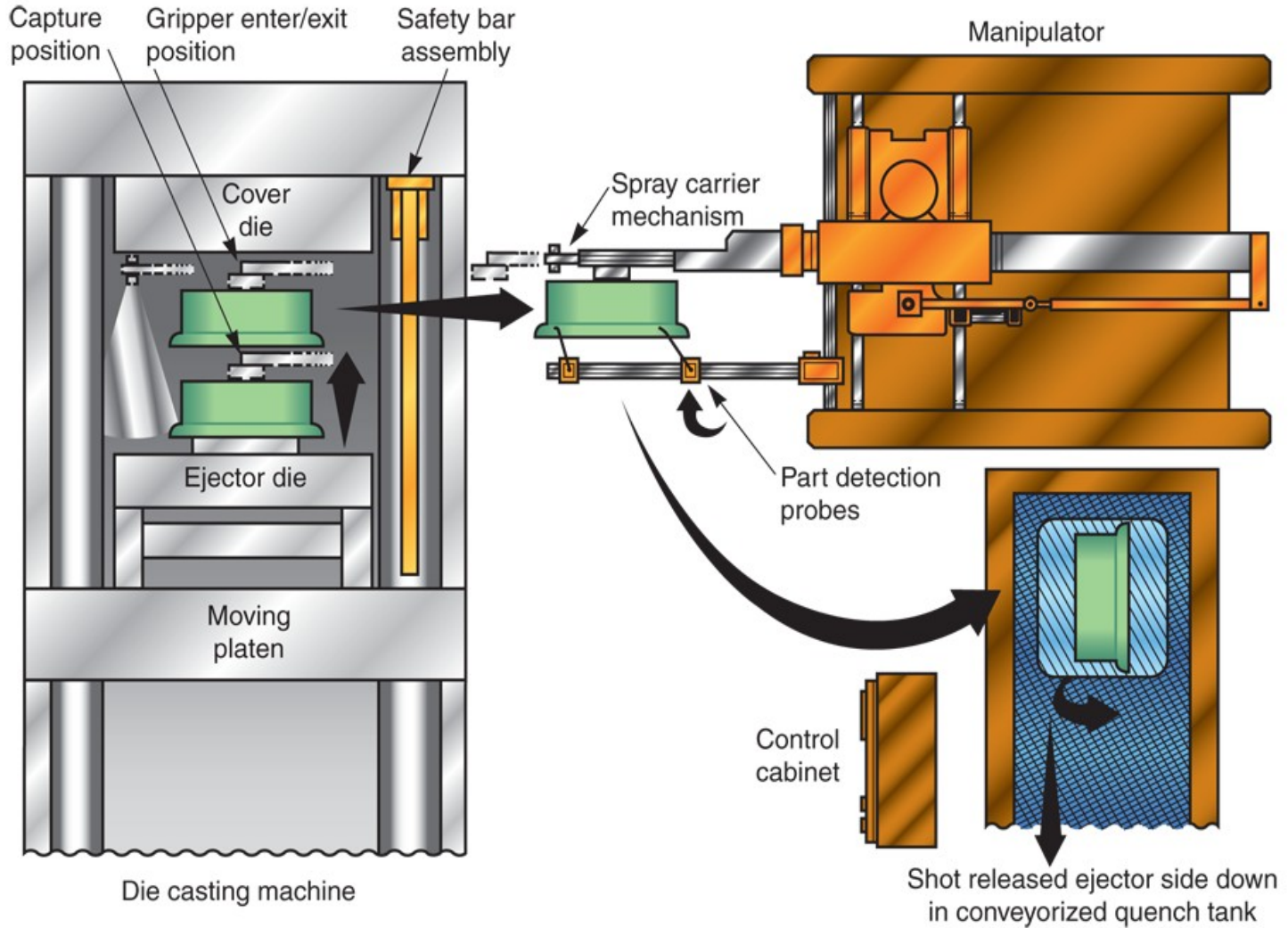
# Robot Applications in Industry

## Loading and Unloading



# Robot Applications in Industry

## Die Casting



# Robot Applications in Industry

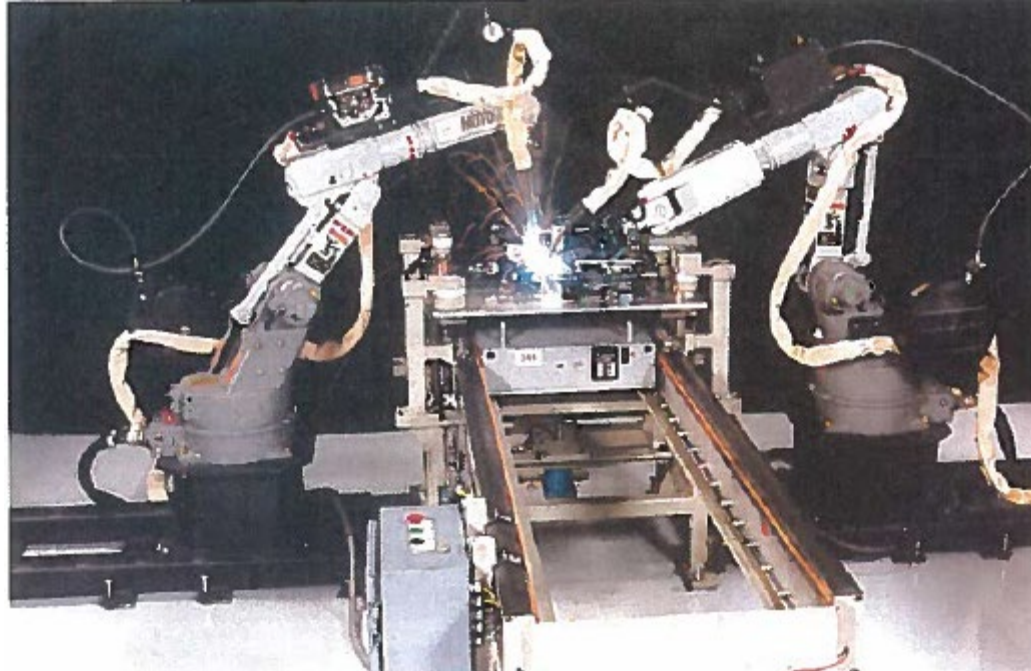
## Welding





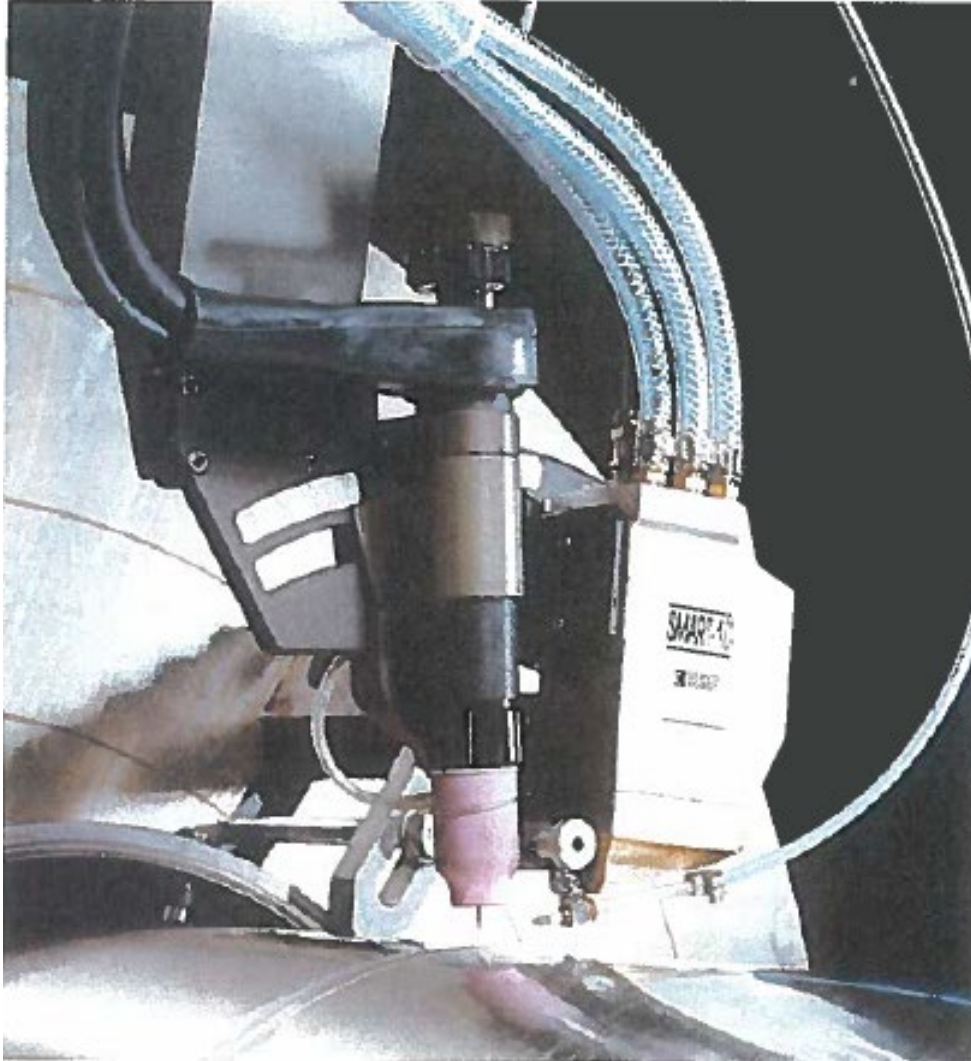
# Robot Applications in Industry

## Unison Welding Operations



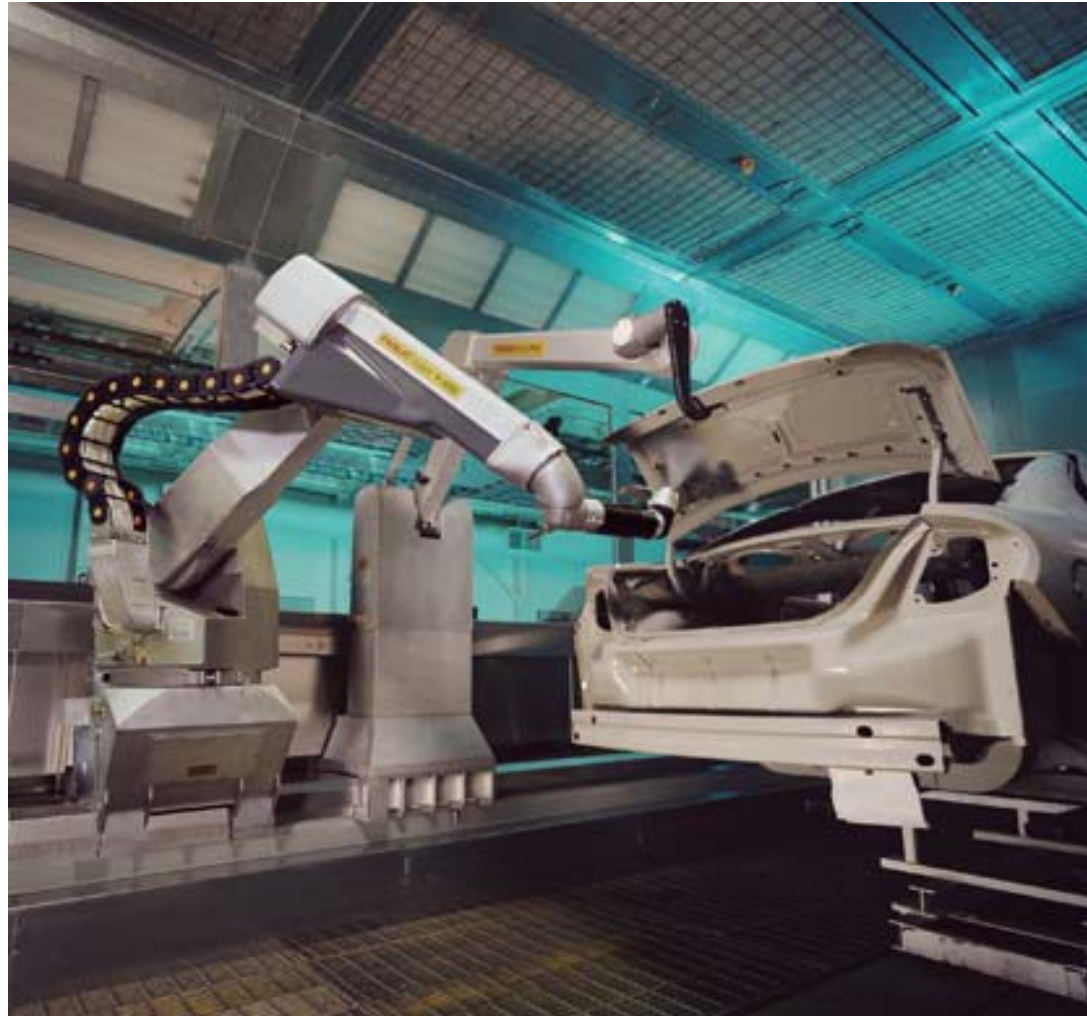
# Robot Applications in Industry

## Laser Guided Welding Operations



# Robot Applications in Industry

## Spray Painting

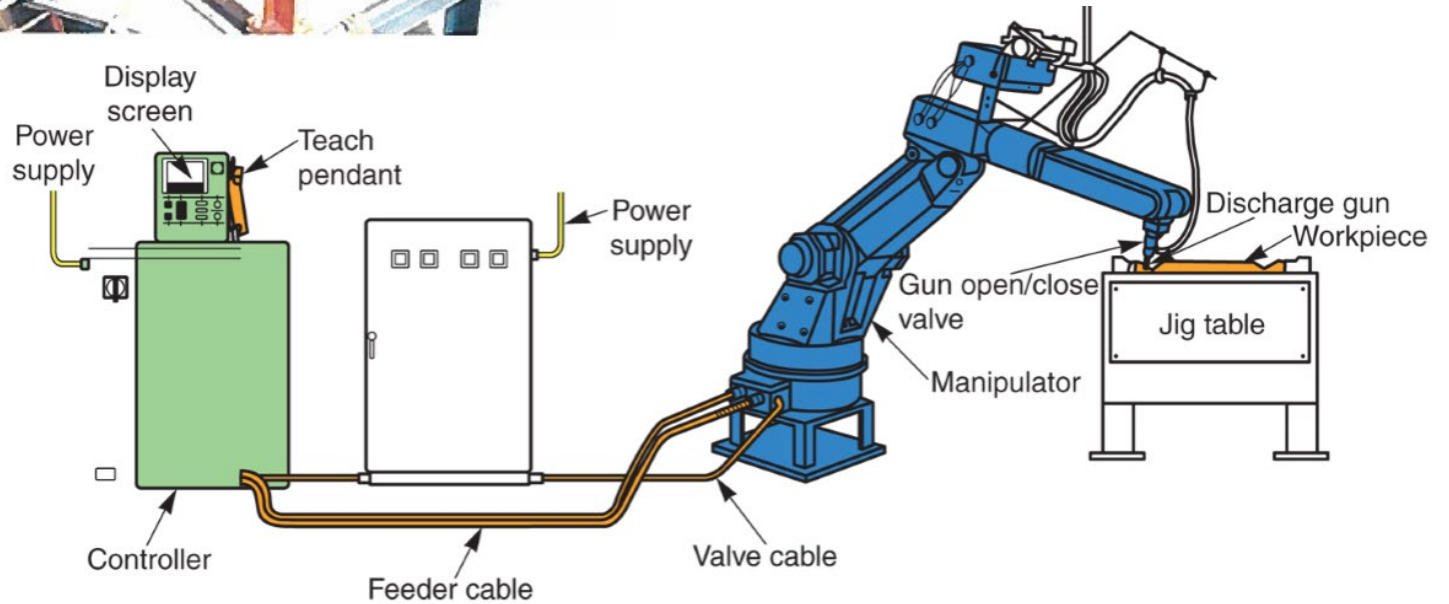




# Robot Applications in Industry



Gluing



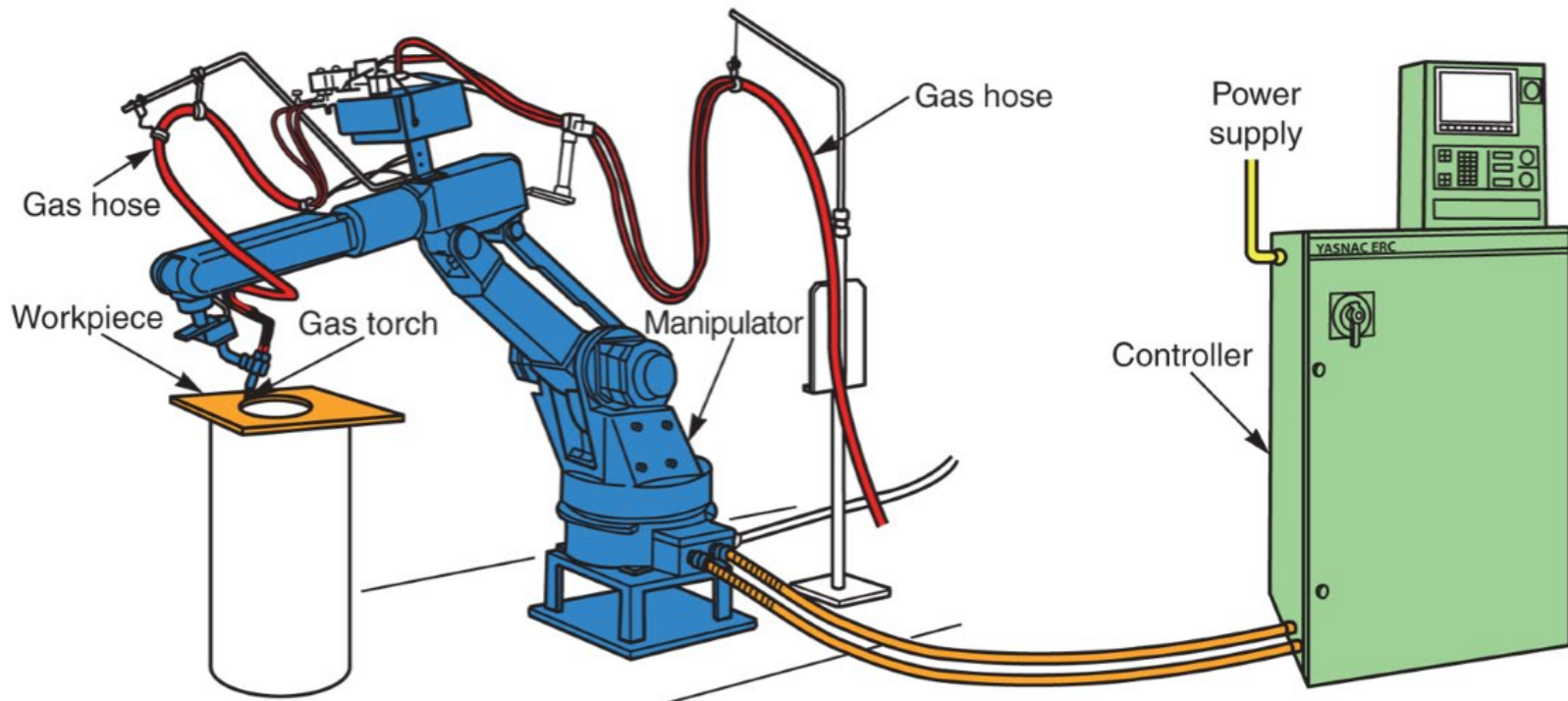
# Robot Applications in Industry

## Laser or Plasma Cutting



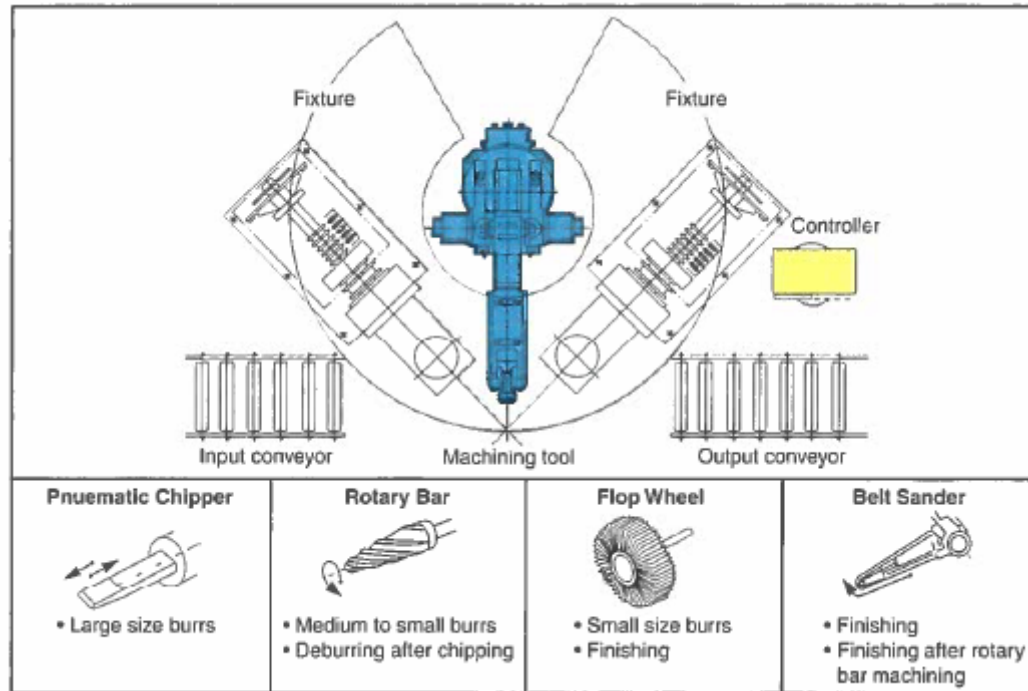
# Robot Applications in Industry

## Gas Torch Cutting / Brazing

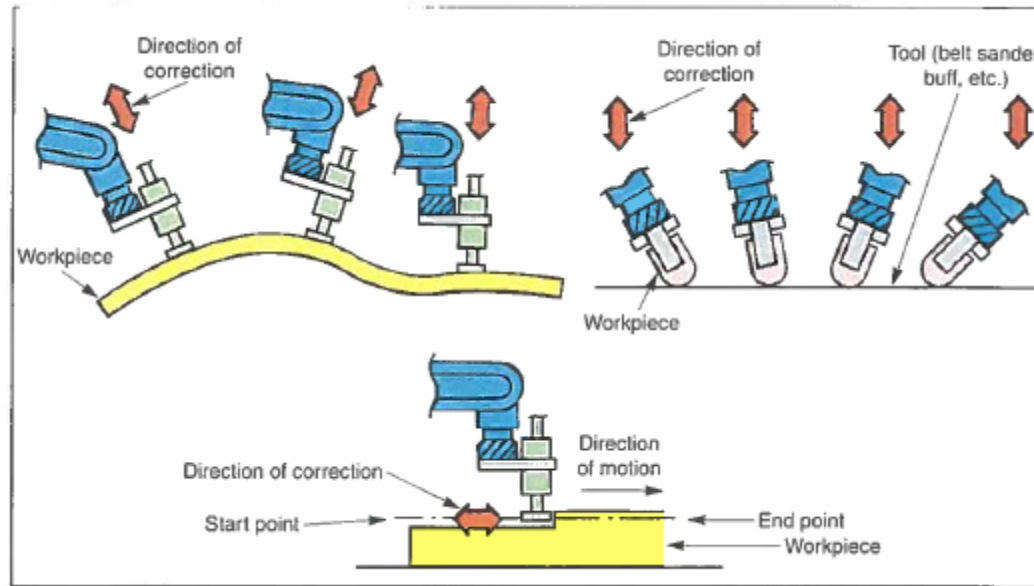


# Robot Applications in Industry

## Robot Machine Processing



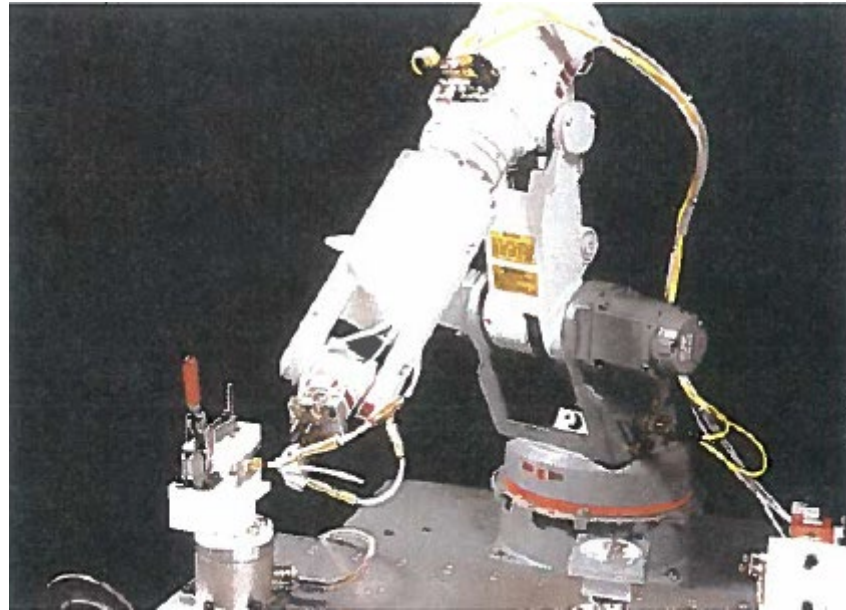
# Force Sensor Correction





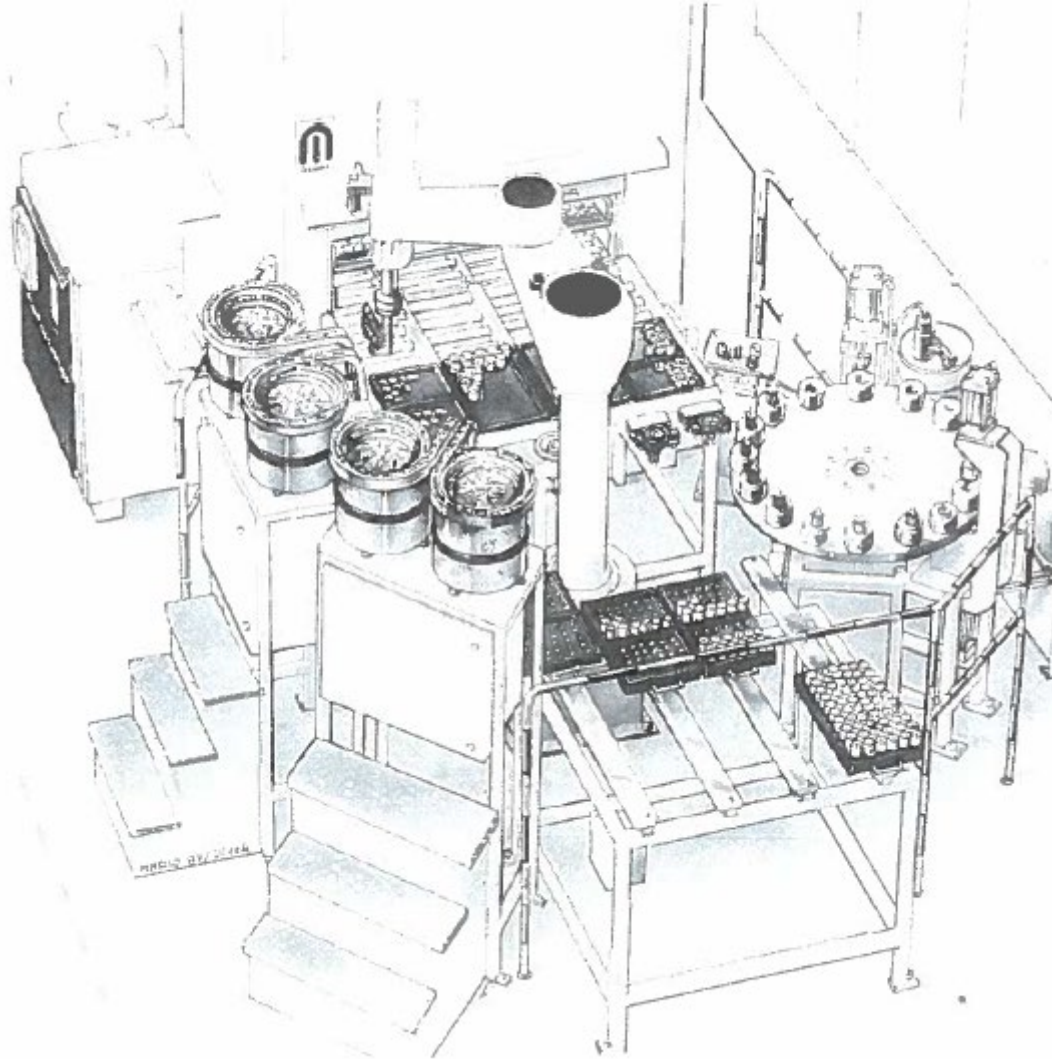
# Robot Applications in Industry

## Robot Assembly Operation



# Robot Applications in Industry

## Work Cell with Camera Vision Systems





# Robot Applications in Industry

## Inspection



**Electronic Sensor Technology Inspects for Defects.**

# Palletizing Robot



# Careers in Robotics: Robotics Engineer



## Careers in Robotics: Robotics Engineer

A robotics engineer designs and maintains robotic systems, and is most often employed in the manufacturing industry. In the area of manufacturing, a robotics engineer may design new robotic systems for a production or assembly line and is likely responsible for maintaining existing robotic systems. Outside manufacturing, employment opportunities include research and robotic system development for military use, mobile exploration, medical applications, solutions for consumers, and many others.

Because robotics engineering relies heavily on computer capabilities and programming, advances in these fields create new opportunities for robotic systems and their applications. From medicine to the military, robots that were once a conceptual design are now reality due to advances in technology and the creativity of robotics engineers.

Typical education for a robotics engineer includes a graduate degree specializing in electrical or mechanical engineering and knowledge of computer science, applied science, and 3D modeling applications. To work in the manufacturing sector, education in or experience with manufacturing processes is also critical for developing and maintaining the robotics systems in a plant. A doctorate degree opens career opportunities in research and highly-specialized system development.

# Robots for Service and Consumer Use

